








# Effects of Planetary Mass Uncertainties on the Interpretation of the Reflectance Spectra of Earth-like Exoplanets

Mario Damiano<sup>1</sup> , Zachary Burr<sup>1</sup> , Renyu Hu<sup>1,2</sup> , Jennifer Burt<sup>1</sup> , and Tiffany Kataria<sup>1</sup> 

<sup>1</sup>Jet Propulsion Laboratory, California Institute of Technology, Pasadena, CA 91109, USA; [mario.damiano@jpl.nasa.gov](mailto:mario.damiano@jpl.nasa.gov)

<sup>2</sup>Division of Geological and Planetary Sciences, California Institute of Technology, Pasadena, CA 91125, USA

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## Abstract

Atmospheric characterization of Earth-like exoplanets through reflected light spectroscopy is a key goal for upcoming direct imaging missions. A critical challenge in this endeavor is the accurate determination of planetary mass, which may influence the measurement of atmospheric compositions and the identification of potential biosignatures. In this study, we used the Bayesian retrieval framework EXOREL<sup>3R</sup> to investigate the impact of planetary mass uncertainties on the atmospheric characterization of terrestrial exoplanets observed in reflected light. Our results indicate that precise prior knowledge of the planetary mass can be crucial for accurate atmospheric retrievals if clouds are present in the atmosphere. When the planetary mass is known within 10% uncertainty, our retrievals successfully identified the background atmospheric gas and accurately constrained atmospheric parameters together with clouds. However, with less constrained or unknown planetary mass, we observed significant biases, particularly in the misidentification of the dominant atmospheric gas. For instance, the dominant gas was incorrectly identified as oxygen for a modern Earthlike planet or carbon dioxide for an Archean Earth-like planet, potentially leading to erroneous assessments of planetary habitability and biosignatures. These biases arise because the uncertainties in planetary mass affect the determination of surface gravity and atmospheric scale height, leading the retrieval algorithm to compensate by adjusting the atmospheric composition. Our findings emphasize the importance of achieving precise mass measurements—ideally within 10% uncertainty—through methods such as extreme precision radial velocity or astrometry, especially for future missions like the Habitable Worlds Observatory.

*Unified Astronomy Thesaurus concepts:* [Exoplanet atmospheric composition \(2021\)](#); [Bayesian statistics \(1900\)](#); [Spectroscopy \(1558\)](#); [Direct imaging \(387\)](#)

## 1. Introduction

The search for potentially habitable worlds has become a paramount objective in space research. Identifying planets that could host life is not only a fascinating scientific endeavor but also a crucial step toward understanding our place in the Universe. In line with this goal, the Astro2020 decadal survey has prioritized the development of a 6 m class telescope designed to image habitable-zone terrestrial exoplanets in reflected light, highlighting its significance for future missions (National Academies of Sciences, Engineering, and Medicine 2021). This telescope, now named “Habitable Worlds Observatory” (HWO), would enable the detection and detailed characterization of potentially Earthlike planets with unprecedented precision, providing insights into their atmospheric composition, surface conditions, and potential habitability.

Accurate knowledge of the planetary mass is shown to be crucial for determining the composition of exoplanetary atmospheres using the transit method, the currently dominating method to characterize exoplanets (N. E. Batalha et al. 2019a). The mass of a planet influences its gravitational pull, atmospheric pressure, and the distribution of gases, all of which affect the observed spectra. Similarly, the knowledge of the planetary mass is presumed to be important for the proper characterization of planets via reflected light (J. Crass et al. 2021), but the specific

dependency of the measurement ability on the planetary mass uncertainties remains unclear.

To address this issue, we explore the impact of planetary mass uncertainties on the atmospheric retrieval of terrestrial exoplanets observed in reflected light. We use EXOREL<sup>3R</sup> (M. Damiano & R. Hu 2020, 2022; M. Damiano et al. 2023) to interpret the spectra of two different atmospheres (i.e., Modern and Archean Earth analogs), and we assess the effect of different planetary mass prior knowledge on the retrieved posterior probability distribution functions.

In the context of reflection spectroscopy, A. Salvador et al. (2024) discussed the impact of orbit and mass uncertainties. A. Salvador et al. (2024) investigated the impact of orbital and mass constraints, derived from precursor radial velocity surveys or astrometry, on the retrievals of small terrestrial planetary properties. They suggested that the prior information on orbital parameters significantly tightens constraints on the planetary radius, and additional mass knowledge does not notably enhance the retrieval of atmospheric or bulk properties. Conversely, our study focuses on the effects of planetary mass and radius uncertainties on the retrievable atmospheric information. A. Salvador et al. (2024) highlighted that a higher signal-to-noise ratio (SNR) could be more beneficial than additional prior mass information for atmospheric characterization. While we do not explore a range of SNR scenarios, our study on the interplay between the mass uncertainty and spectral information complements the work presented in A. Salvador et al. (2024).

EXOREL<sup>3R</sup> has already proven to be a valuable tool for characterizing terrestrial exoplanets in reflected light



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(M. Damiano & R. Hu 2022). This study builds on that foundation by introducing several enhancements to the retrieval software and addressing key scientific questions. Our retrieval framework incorporates advanced statistical methods to derive atmospheric parameters from spectral data, preserving the causal relationships between observed spectral features and underlying atmospheric properties. By applying EXOREL<sup>3</sup>, we aim to quantify the impact of mass and radius uncertainties on the retrieval accuracy and identify the most valuable precursor observational parameters for future missions.

This paper is structured as follows: Section 2 discusses the setup of the retrievals, key upgrades to EXOREL<sup>3</sup>, and the various atmospheric scenarios explored in this study. In Section 3, we present the retrieval results, highlighting the influence of mass and radius uncertainties on the derived atmospheric properties. Section 4 articulates the implications of these findings for the development of future missions. Finally, Section 5 summarizes the key points of this work, emphasizing the importance of accurate mass and radius measurements for the successful characterization of terrestrial exoplanets in reflected light.

## 2. Methods

We used EXOREL<sup>3</sup> to explore the relationship between mass–radius uncertainties and posterior constraints from retrievals of reflected light spectra. EXOREL<sup>3</sup> is a Bayesian inverse retrieval framework for spectroscopically directly imaged exoplanets (M. Damiano & R. Hu 2020, 2022; M. Damiano et al. 2023). A radiative transfer model is used to generate spectra, which are compared with the observed spectra. The free parameters are systematically varied to determine what combination will produce spectra closest to the observed spectra. In this way, key parameters such as gas abundances and the size of the planet can be determined from its spectrum.

### 2.1. Upgrades to EXOREL<sup>3</sup>

Compared to our previous works, we introduced a series of upgrades to the EXOREL<sup>3</sup> software to carry out this study.

#### 2.1.1. Cloud Fraction

The cloud fraction has been introduced as a parameter in our forward model. Although cloud density is self-consistently calculated within EXOREL<sup>3</sup> so that the transparency of the cloud can be modeled, the cloud coverage of the integrated planetary disk was assumed to be 100% (M. Damiano & R. Hu 2020). Previously, the cloud transparency/density could not reproduce the behavior of patchy clouds as the cloud formulation carries spectral features from water vapor condensation. Now, we calculate two models: one with the original cloud formulation and the other that is free from clouds. We take the average of the two models, weighted by the cloud fraction, as the modeled reflected spectrum. This change effectively moves EXOREL<sup>3</sup> from a 1D model to a 1.5D model as now two atmospheric columns are taken into consideration to calculate the model reflected light. In this manuscript, we fixed the cloud fraction to 25%. The effect of having cloud fraction as a free parameter will be explored in a companion study (Z. Burr et al. 2025, in preparation).

#### 2.1.2. Rayleigh Scattering

Another upgrade we introduced is the ability to calculate the Rayleigh scattering according to the atmospheric composition. The contribution to the Rayleigh scattering of each of the gases is taken into account, and the total Rayleigh scattering is the weighted average of the Rayleigh scattering due to each of the individual gases based on the volume mixing ratios of the gases. The Rayleigh scattering is important to constrain the dominant gas of the atmosphere, especially if the gas does not show significant spectral features in the considered wavelength range (near-ultraviolet or NUV, visible or VIS, and near-infrared or NIR), e.g., N<sub>2</sub> and H<sub>2</sub>. Additionally, the Rayleigh scattering is sensitive to the amount of clouds as these tend to mute the spectral feature of Rayleigh scattering. When we include a cloud-free column in the forward model, a Rayleigh slope in the spectrum will typically result in a strong reflection at a shorter wavelength and thus the need for “retrieving” Rayleigh scattering.

#### 2.1.3. Adaptive Vertical Grid of Model Atmosphere

In the context of radiative transfer calculation, the layering of the vertical profile plays a crucial role. The more layers the atmosphere is divided into, the more precise the calculation of the energy transfer will be, resulting in a more precise synthesized spectrum. However, the bigger the number of layers, the more computationally intensive the calculation is. In the context of retrieval calculations a balance between these two effects should be employed to reach good precision in the calculations while being sufficiently fast. Generally, the layers are equally spaced in the planetary scale height, and when translated into physical height, more layers are located in the upper part of the atmosphere. While this is a good practice to capture the absorption features of the atmospheric gases, it might create a situation in which the clouds and the atmosphere beneath are poorly sampled, which will create distortion in the calculated albedo spectrum. In literature, e.g., N. E. Batalha et al. (2019b), this issue has been solved by linking the number of layers in which the cloud is defined with the optical thickness of the cloud ( $\tau_c$ ). In EXOREL<sup>3</sup>,  $\tau_c$  is not a free parameter, and so we decided to approach the problem from a different angle. We defined a grid of layers with the same number of layers above, within, and below the cloud layer regardless of the vertical position of the clouds. In this way, we always ensure that there are enough layers to fully describe radiative transfer within the cloud layer. We refer to this new scheme in this manuscript as the “adaptive grid.” For the rest of this manuscript, we used 80 layers in this adaptive grid scheme. This new scheme allows us to reduce the computation time as each of the spectra in the retrieval do not require a large number of layers (200+). As an example, with this new scheme we observed that the adaptive grid with 100 layers produces the same spectrum as a standard grid with 500 layers.

#### 2.1.4. Partial Pressure Sampling

In literature, when retrieving the concentration of molecular species, the volume mixing ratio (VMR) is generally the most direct expression that can be used. This scheme works well when giant planets are considered as H<sub>2</sub> is implicitly adopted as the dominant gas of the atmosphere. When moving toward small planets, a wider range of bulk atmospheric compositions needs to be taken into consideration, and the dominant gas is

not trivial (e.g., R. Hu & S. Seager 2014). In this regime, the centered-log-ratio (CLR) can be used to leverage its advantage on compositional analysis (B. Benneke & S. Seager 2012; M. Damiano & R. Hu 2021). These two methods have worked well for planets observed via transmission and/or emission spectroscopy. In reflection spectroscopy, we do not define the radius of the planet at a specific pressure (as is done in transmission spectroscopy, for example) because we are sensitive to the surface pressure, which is linked with the planetary radius. In this work, we did not fit the surface pressure, and instead we introduced the partial pressure of the gases as free parameters (A. Salvador et al. 2024). The sum of the gas partial pressures is the surface pressure by definition (see Equations (1) and (2)):

$$P_0 = \sum_n \delta P_{\text{gas}_n} \quad (1)$$

$$\delta P_{\text{gas}_n} = P_0 \times \text{VMR}_{\text{gas}_n} \quad (2)$$

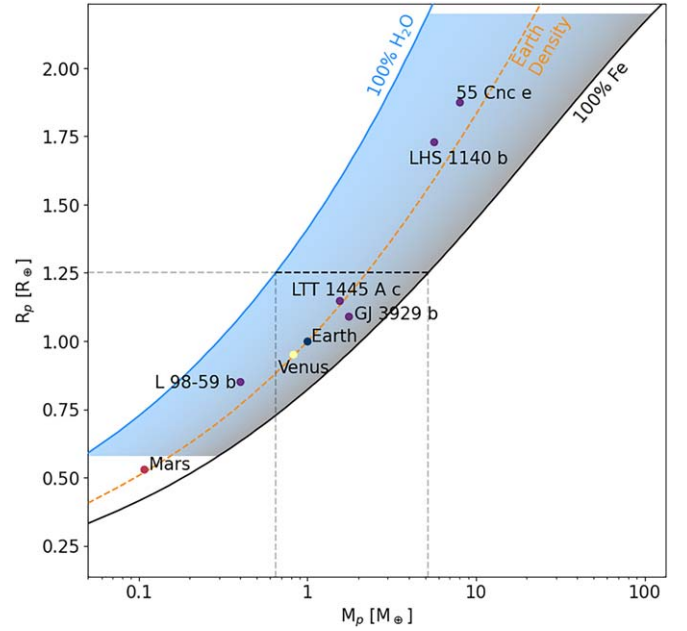
where  $\delta P_{\text{gas}_n}$  is the partial pressure of the  $n$ th gas,  $\text{VMR}_{\text{gas}_n}$  is the  $n$ th gas volume mixing ratio, and  $P_0$  is the surface pressure.

Using the partial pressure to define the atmospheric composition gives the advantage of removing the need for the concept of a filler gas, as all the gas partial pressures are free and independent parameters, including those that are not spectroscopically active in the considered wavelength range. Another advantage is the ease of switching from the partial pressure space to the VMR space, as the transformation is linear. When CLR is used, the transformation to VMR is not linear, and nonuniform priors may be required (M. Damiano & R. Hu 2021).

### 2.1.5. Planetary Mass as Free Parameter

Given the focus on this parameter in this study, we defined and explored different prior probability functions. A novel type of prior function, the “2D prior,” is introduced, which leverages the correlation between planetary mass and radius. This conditional mass–radius prior relation was adopted from L. Zeng et al. (2016) models (see Figure 1). The planetary radius has a uniform prior, and for a given radius, the mass is drawn from a uniform distribution between the corresponding mass for a 100% iron planet to the corresponding mass for a 100% water ice planet. These two cases represent the theoretical upper and lower bounds on density for a terrestrial planet. This 2D prior limits the search space to only physically realistic scenarios, enabling better fitting of the planetary mass than the independent uniform prior. By using this prior function, we are introducing information into our retrieval process that is physically motivated. When using the 2D prior, the uniform distribution for radius is decreased from  $[0.5, 10] R_{\oplus}$  to  $[0.58, 2.2] R_{\oplus}$ , as this is the range that the models of L. Zeng et al. (2016) cover.

Additionally, we also consider the simplest prior for the planetary mass: a uniform flat prior between two fixed values  $[0.01, 20] M_{\oplus}$ , as well as a Gaussian prior to simulate a situation where the mass uncertainty is provided (e.g., with radial velocity measurements). In this study, we considered two Gaussian priors that correspond to a  $3.3\sigma$  or  $10\sigma$  detection of the planetary mass.



**Figure 1.** Mass–radius relations used for the 2D prior (L. Zeng et al. 2016). The shaded region shows the full search space of the retrieval when using this prior function. The radius is chosen from a uniform distribution between 0.58 and  $2.2 R_{\oplus}$ , then the mass is chosen from a uniform distribution between the corresponding mass for a 100% water ice planet and a 100% iron planet with this radius. For example, for a radius of  $1.25 R_{\oplus}$ , the mass can vary from 0.65 to  $5.2 M_{\oplus}$ .

### 2.2. Retrieval Setup

In this study, the partial pressure of  $\text{H}_2\text{O}$ ,  $\text{CH}_4$ ,  $\text{CO}_2$ ,  $\text{O}_2$ ,  $\text{O}_3$ , and  $\text{N}_2$  are considered as free parameters, and we transform the partial pressures into VMR in the posterior distribution graphs shown in this paper. We consider water clouds as the only condensates. The clouds are modeled as described in M. Damiano & R. Hu (2020) and are fit with the cloud top pressure ( $P_{\text{top},\text{H}_2\text{O}}$ ), cloud depth ( $D_{\text{cloud},\text{H}_2\text{O}}$ ), and condensation ratio ( $CR_{\text{H}_2\text{O}}$ ), as well as the VMR of water below the clouds. We also included a variation in which the cloud particle size is additionally considered as a free parameter. In EXOREL<sup>3A</sup>, the particle size is typically estimated based on microphysics (R. Hu 2019). By including a free particle size, we assume instead a constant average value across the atmosphere. The planetary mass and the planetary radius are included as free parameters, as described in Section 2.1.5.

Table 1 lists the free parameters, the prior space used, and the range in which the parameters are probed. EXOREL<sup>3A</sup> uses MultiNest (F. Feroz et al. 2009) to sample the Bayesian evidence, estimate the parameters, and calculate the posterior distribution functions. MultiNest is used through its Python implementation pymultinest (J. Buchner et al. 2014). For all the retrieval analyses presented here, we used 2000 live points and 0.5 as the Bayesian evidence tolerance.

### 2.3. Atmospheric and Observational Scenarios

To study the effect of different mass uncertainties on the interpretation of the atmospheric characterization, we used three different terrestrial planet scenarios:

1. A cloud-free modern Earthlike atmosphere.  $\text{N}_2$  dominated ( $\sim 79\%$ ) with  $\text{O}_2$  ( $\sim 20\%$ ) and trace amounts of  $\text{H}_2\text{O}$ ,  $\text{O}_3$ ,  $\text{CH}_4$ , and  $\text{CO}_2$  (see Table 2);



**Table 1**

Model Parameters and Prior Probability Distributions Used in the Atmospheric Retrievals

| Parameter   | Symbol                        | Prior  |
|---|-------------------------------|--|
| Cloud top pressure [Pa]   | $P_{\text{top,H}_2\text{O}}$  | $\mathcal{LU}(2.0, 7.0)$   |
| Cloud depth [Pa]  | $D_{\text{clid,H}_2\text{O}}$ | $\mathcal{LU}(2.0, 7.0)$   |
| Condensation ratio  | $CR_{\text{H}_2\text{O}}$     | $\mathcal{LU}(-7.0, 0.0)$  |
| Partial pressure H <sub>2</sub> O [Pa]                                  | PP (H <sub>2</sub> O)         | $\mathcal{LU}(-7.0, 7.0)$  |
| Partial pressure CH <sub>4</sub> [Pa]                                   | PP (CH <sub>4</sub> )         | $\mathcal{LU}(-7.0, 7.0)$  |
| Partial pressure CO <sub>2</sub> [Pa]                                   | PP (CO <sub>2</sub> )         | $\mathcal{LU}(-7.0, 7.0)$  |
| Partial pressure O <sub>2</sub> [Pa]                                    | PP (O <sub>2</sub> )          | $\mathcal{LU}(-7.0, 7.0)$  |
| Partial pressure O <sub>3</sub> [Pa]                                    | PP (O <sub>3</sub> )          | $\mathcal{LU}(-7.0, 7.0)$  |
| Partial pressure N <sub>2</sub> [Pa]                                    | PP (N <sub>2</sub> )          | $\mathcal{LU}(-7.0, 7.0)$  |
| Planetary mass [ $M_{\oplus}$ ]   | $M_p$                         | $\mathcal{U}(0.01, 20.0)$<br>$\mathcal{N}(1.0, \sigma_{M_p}^2)$<br>2D prior <sup>a</sup> |
| Planetary radius [ $R_{\oplus}$ ]<br>(when using the 2D prior for mass) | $R_p$                         | $\mathcal{U}(0.5, 10.0)$<br>$\mathcal{U}(0.58, 2.2)$                                     |

**Notes.**  $\mathcal{U}(a, b)$  is the uniform distribution between values  $a$  and  $b$ ,  $\mathcal{LU}(a, b)$  is the log-uniform (Jeffreys) distribution between values  $a$  and  $b$ , and  $\mathcal{N}(\mu, \sigma^2)$  is the normal distribution with mean  $\mu$  and variance  $\sigma^2$ .

<sup>a</sup> L. Zeng et al. (2016).

2. *A modern Earthlike atmosphere.* N<sub>2</sub> dominated (~79%) with O<sub>2</sub> (~20%) and trace amounts of H<sub>2</sub>O, O<sub>3</sub>, CH<sub>4</sub>, and CO<sub>2</sub>, and a cloud deck at ~0.6 bar with a cloud fraction of 25% (see Table 3);
3. *An Archean Earth-like atmosphere.* The Earth's atmosphere as it was approximately 4–2.5 billion yr ago. Similar to the modern Earth, but with less O<sub>2</sub> and considerably more CH<sub>4</sub> and CO<sub>2</sub> (see Table 4).

For all the scenarios,  $1 M_{\oplus}$ ,  $1 R_{\oplus}$ , 1 au, and 60 deg phase angle were adopted. We considered five retrieval scenarios: a case in which the mass is fully known and the radius is a free parameter along with other atmospheric parameters, and four scenarios in which the planetary mass is a free parameter and varying different prior functions as listed in Table 1. Additionally, for the modern Earthlike and Archean Earthlike, we ran an additional case in which the particle size is a free parameter instead of being self-consistently calculated. The spectra are generated in the NUV from 0.25 to 0.4  $\mu\text{m}$  at  $R = 7$ , the VIS from 0.45 to 1.0  $\mu\text{m}$  at  $R = 140$ , and NIR from 1.0 to 1.8  $\mu\text{m}$  at  $R = 70$ . This is consistent with previous mission concept studies (A. Roberge & L. A. Moustakas 2018; B. S. Gaudi et al. 2020).

A new noise model was developed for this work, which is explained in more detail in the Appendix. The model includes the wavelength-dependent behavior of noises in high-contrast imaging. It represents a simple limiting case with very good starlight suppression and low detector noise, in which photon noise from the astrophysical scene dominates. We follow the analytic prescription outlined in T. D. Robinson et al. (2016). We assume exozodi dominate over local zodi, and neglect local zodi. Dark current is also ignored, assuming that a future exoplanet imaging mission will have good enough detectors that the dark current will be lower than photon noise at all wavelengths, as is already the case for the Roman CGI in broadband imaging (P. Morrissey et al. 2023). The speckle residuals are likewise neglected. This leaves the shot noise from the planet and the exozodi as the only remaining noise sources. The model is scaled to an SNR of 20 at 0.75  $\mu\text{m}$ . This

noise model defines the error bars of the synthesized spectra, and corresponding Gaussian noise is added to simulate a realistic observation. After simulating the reflected light spectra and generating the synthetic data (Figure 2), we proceeded to run EXOREL<sup>3R</sup> for each scenario previously described in Section 2. Tables 2, 3, and 4 report the numerical values of the retrieval scenarios considered in this work.

### 3. Results

#### 3.1. Cloud-free Modern Earthlike

Without clouds as a complicating factor, EXOREL<sup>3R</sup> is able to correctly determine all the free variables (i.e., the truth value is included within the posterior distribution functions) in all scenarios (see Figure 3). The background gas is correctly determined to be N<sub>2</sub>, with O<sub>2</sub> being the second most abundant. The radius is very tightly constrained (to within 1%) in all scenarios.

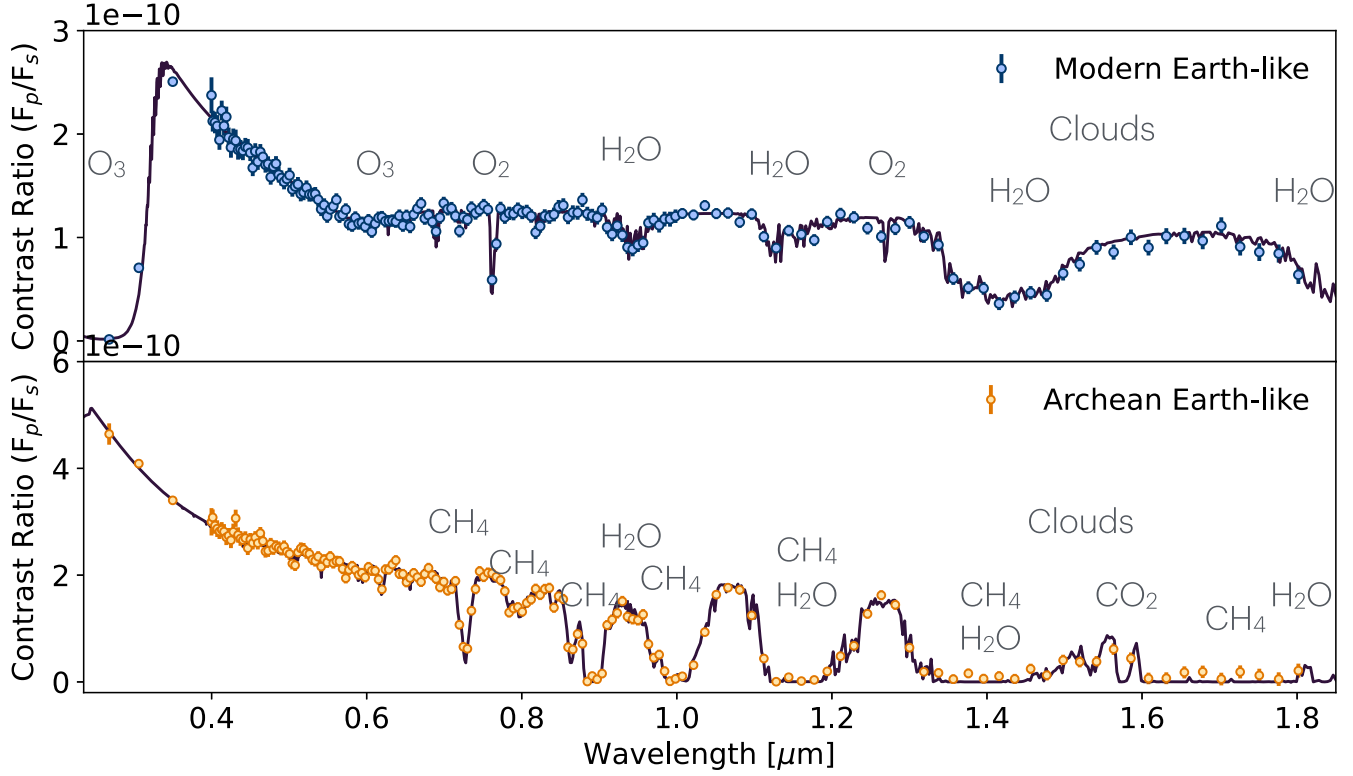
Zooming in on just the planetary mass, radius, and surface pressure (Figure 4), we do not find correlations between planetary mass and radius. However, there is a strong positive correlation between mass and surface pressure, indicating that the spectrum is approximately sensitive to the column abundances ( $\sim P/g$ ). For the unknown prior, the 2D prior, and the 30% Gaussian prior, the mass is constrained to  $1 \pm 0.2 M_{\oplus}$ . This shows that some knowledge of the mass can be derived from the spectrum itself. The 10% Gaussian prior has tighter constraints on the mass than what can be derived from the spectrum, which also translates into a slightly better constraint on the surface pressure. In the case of perfect mass knowledge, the surface pressure has the tightest constraint. The surface pressure is a derived parameter and it is linked to the sum of the partial pressure of the single gases in the atmosphere. Therefore the planetary mass correlates with the atmosphere composition overall. For example, a looser constraint on the planetary mass results in a slightly higher variance in the posterior distribution of water vapor.

#### 3.2. Modern Earthlike

Stepping up the complexity, we then took into consideration the Modern Earth case with the addition of a cloud deck. The presence of a cloud deck introduces uncertainty in the retrieval process: clouds can obscure the Rayleigh scattering slope, which is the primary feature used to constrain the abundance of N<sub>2</sub>. Furthermore, clouds can obscure the planetary surface, complicating the determination of the planetary radius.

In the first scenario, we assume perfect knowledge of the planetary mass. This scenario serves as our baseline, against which subsequent scenarios are compared. As expected, all the true values have been accurately retrieved in the baseline scenario except for a small bias in the position of the cloud layer, but still within  $3\sigma$  (see Figure 7). The retrieved atmosphere is N<sub>2</sub> dominated, with a significant amount of O<sub>2</sub>, followed by approximately 1% H<sub>2</sub>O. The cloud deck is correctly retrieved within  $3\sigma$  of the true value, and the planetary radius is well constrained at  $1 R_{\oplus}$ .

When the planetary mass is treated as a free parameter, we observe that the mass posteriors converge to values substantially smaller than the truth unless the prior mass constraints are  $10\sigma$ . In tandem with the biased mass estimate, the background gas is incorrectly identified as oxygen instead of nitrogen (Figure 7). This misidentification likely arises because the



**Figure 2.** Simulated spectra and data models for the Modern and Archean Earth-like scenarios. The data points are obtained by binning the synthesized model and by applying Gaussian noise and error bars as defined in the [Appendix](#). Top panel: modern Earthlike. Bottom panel: Archean Earth-like.

**Table 2**  
Atmospheric Parameters Used to Simulate the Modern Earthlike (Cloud-free) Scenario and the Retrieval Results for the Five Scenarios Considered

| Parameter                                     | Input | Perfect $M_p$           | Unknown $M_p$           | 2D Prior                | Gaussian Prior (30%)    | Gaussian Prior (10%)    |
|---|-------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|
| $\text{Log}(P_0)$ [Pa] (derived)              | 5.00  | $5.01^{+0.02}_{-0.01}$  | $5.03^{+0.08}_{-0.09}$  | $5.01^{+0.09}_{-0.12}$  | $5.01^{+0.07}_{-0.09}$  | $5.01^{+0.04}_{-0.04}$  |
| $\text{Log}(\text{VMR}_{\text{H}_2\text{O}})$ | -2.52 | $-2.56^{+0.04}_{-0.04}$ | $-2.57^{+0.05}_{-0.06}$ | $-2.56^{+0.07}_{-0.07}$ | $-2.56^{+0.06}_{-0.06}$ | $-2.56^{+0.04}_{-0.04}$ |
| $\text{Log}(\text{VMR}_{\text{CH}_4})$        | -5.70 | $-5.76^{+0.55}_{-3.85}$ | $-5.75^{+0.54}_{-3.64}$ | $-5.76^{+0.54}_{-3.65}$ | $-5.81^{+0.60}_{-3.92}$ | $-5.85^{+0.63}_{-3.91}$ |
| $\text{Log}(\text{VMR}_{\text{CO}_2})$        | -3.40 | $-5.54^{+2.24}_{-4.41}$ | $-5.38^{+2.09}_{-4.48}$ | $-5.71^{+2.40}_{-4.30}$ | $-5.73^{+2.42}_{-4.33}$ | $-5.54^{+2.24}_{-4.50}$ |
| $\text{Log}(\text{VMR}_{\text{O}_2})$         | -0.67 | $-0.62^{+0.08}_{-0.08}$ | $-0.65^{+0.10}_{-0.11}$ | $-0.63^{+0.11}_{-0.12}$ | $-0.63^{+0.10}_{-0.10}$ | $-0.62^{+0.09}_{-0.09}$ |
| $\text{Log}(\text{VMR}_{\text{O}_3})$         | -6.15 | $-6.14^{+0.02}_{-0.02}$ | $-6.14^{+0.02}_{-0.02}$ | $-6.14^{+0.02}_{-0.02}$ | $-6.14^{+0.02}_{-0.02}$ | $-6.14^{+0.02}_{-0.02}$ |
| $\text{Log}(\text{VMR}_{\text{N}_2})$         | -0.11 | $-0.12^{+0.02}_{-0.03}$ | $-0.11^{+0.03}_{-0.03}$ | $-0.12^{+0.03}_{-0.04}$ | $-0.12^{+0.03}_{-0.04}$ | $-0.12^{+0.02}_{-0.03}$ |
| $M_p [M_\oplus]$                              | 1.00  | ...                     | $1.06^{+0.22}_{-0.20}$  | $1.00^{+0.25}_{-0.26}$  | $1.00^{+0.19}_{-0.19}$  | $1.00^{+0.08}_{-0.08}$  |
| $R_p [R_\oplus]$                              | 1.00  | $1.01^{+0.01}_{-0.01}$  | $1.00^{+0.01}_{-0.01}$  | $1.00^{+0.01}_{-0.01}$  | $1.00^{+0.01}_{-0.01}$  | $1.00^{+0.01}_{-0.01}$  |
| $\mu [\text{g mol}^{-1}]$ (derived)           | 28.83 | $28.95^{+0.21}_{-0.17}$ | $28.89^{+0.23}_{-0.20}$ | $28.92^{+0.27}_{-0.22}$ | $28.93^{+0.24}_{-0.20}$ | $28.94^{+0.21}_{-0.18}$ |

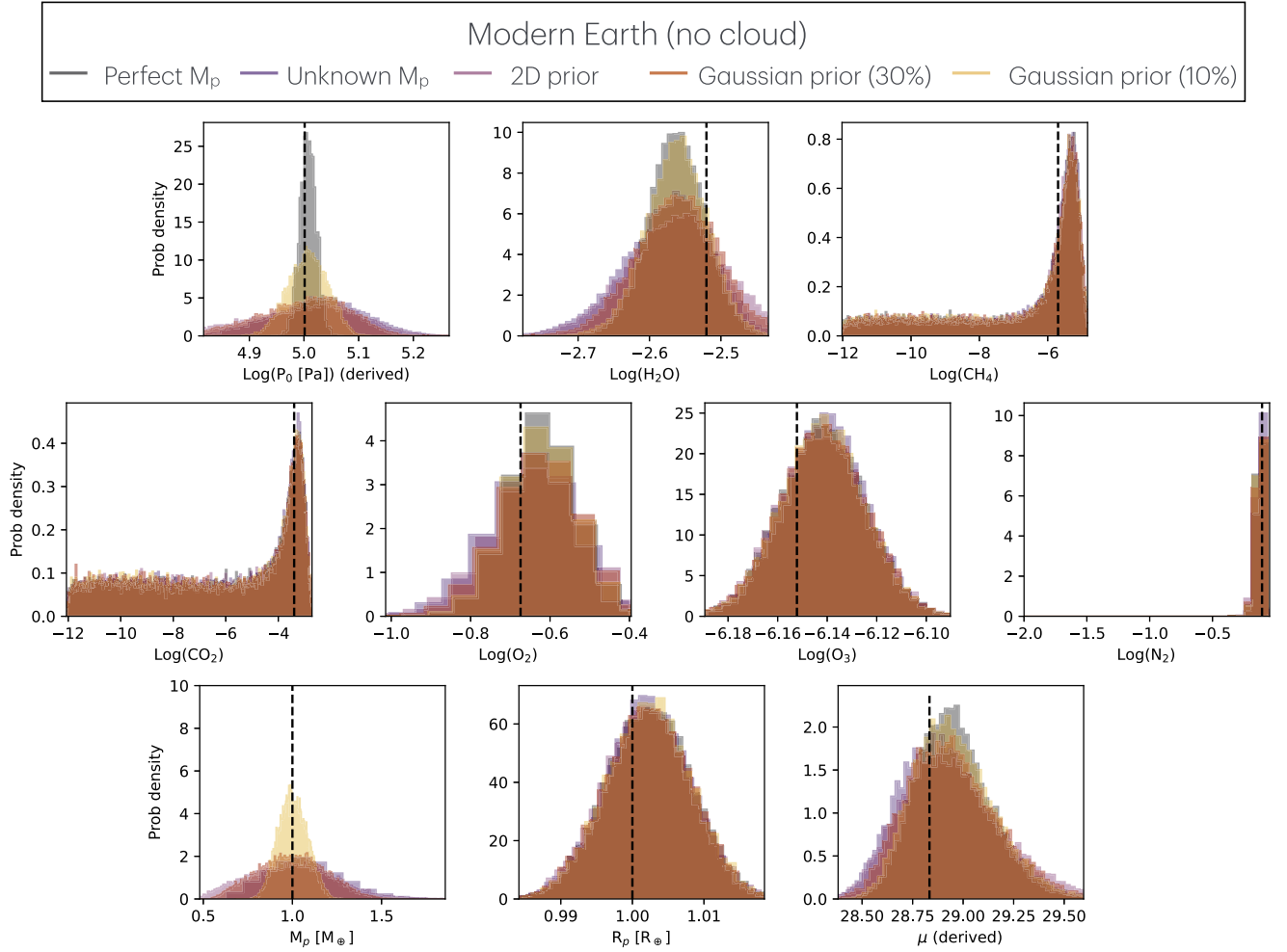
**Note.** The error bars of the retrieval median results correspond to the 68% confidence interval (i.e.,  $1\sigma$ ).

Rayleigh scattering slope at low wavelengths is similar for  $\text{O}_2$  and  $\text{N}_2$ , and the slope is impacted by the planetary mass and can be obscured by clouds. While the other gases were mostly retrieved correctly (e.g., the true values bracketed by posterior distributions), we find a slight bias in the retrieved mixing ratio of ozone. Methane ( $\text{CH}_4$ ) and carbon dioxide ( $\text{CO}_2$ ) may, in some cases, be loosely constrained, as their abundances are low enough to not produce significant absorption features that can be fully interpreted by the retrieval. Additionally, the cloud deck was retrieved at a higher altitude by about an order of magnitude.

Again, we observe correlations between the planetary mass, radius, and surface pressure (Figure 5). Here, the relationship appears linear when the surface pressure is expressed in

logarithmic space and the mass in linear space. Similarly, we observe a comparable behavior between the planetary radius and surface pressure, which translates into a correlation between mass and radius (Figure 5). Physically, this behavior can be explained by considering that a less massive planet has a lower surface gravity; thus, a lower pressure above the cloud deck is required to maintain the same atmospheric column in number density.

Additionally, we also consider a variation of this scenario in which we also set the cloud particle size as a free parameter. When the particle size is retrieved to a constant average value throughout the atmosphere, it reveals additional effects in the constraints of mass, radius, and surface pressure (Figure 6). We observe that the posterior



**Figure 3.** Posterior distribution functions of the Bayesian analysis on the cloud-free modern Earthlike reflected spectrum of all scenarios defined in Section 2.1.5.

**Table 3**  
Atmospheric Parameters Used to Simulate the Modern Earthlike Scenario and the Retrieval Results for the Five Scenarios Considered

| Parameter                                     | Input | Perfect $M_p$           | Unknown $M_p$           | 2D Prior                   | Gaussian Prior (30%)       | Gaussian Prior (10%)     |
|---|-------|-------------------------|-------------------------|----------------------------|----------------------------|--------------------------|
| $\text{Log}(P_0)$ [Pa] (derived)              | 5.00  | $4.98^{+0.03}_{-0.04}$  | $4.69^{+0.09}_{-0.10}$  | $4.62^{+0.06}_{-0.04}$     | $4.57^{+0.09}_{-0.08}$     | $4.96^{+0.03}_{-0.03}$   |
| $\text{Log}(P_{\text{top,H}_2\text{O}})$ [Pa] | 4.78  | $4.58^{+0.08}_{-0.09}$  | $3.95^{+0.11}_{-0.14}$  | $3.91^{+0.08}_{-0.12}$     | $3.99^{+0.09}_{-0.10}$     | $4.69^{+0.05}_{-0.06}$   |
| $\text{Log}(D_{\text{cld,H}_2\text{O}})$ [Pa] | 4.00  | $4.36^{+0.09}_{-0.09}$  | $3.91^{+0.09}_{-0.09}$  | $3.86^{+0.11}_{-0.14}$     | $3.65^{+0.15}_{-0.15}$     | $4.24^{+0.08}_{-0.14}$   |
| $\text{Log}(\text{CR}_{\text{H}_2\text{O}})$  | -3.50 | $-6.06^{+0.72}_{-0.57}$ | $-5.05^{+0.89}_{-0.84}$ | $-5.15^{+0.81}_{-0.90}$    | $-5.05^{+1.30}_{-1.16}$    | $-4.82^{+1.0}_{-0.81}$   |
| $\text{Log}(\text{VMR}_{\text{H}_2\text{O}})$ | -2.52 | $-2.67^{+0.07}_{-0.06}$ | $-2.48^{+0.06}_{-0.05}$ | $-2.48^{+0.06}_{-0.05}$    | $-2.48^{+0.08}_{-0.07}$    | $-2.61^{+0.06}_{-0.05}$  |
| $\text{Log}(\text{VMR}_{\text{CH}_4})$        | -5.70 | $-6.17^{+0.51}_{-0.48}$ | $-5.65^{+0.33}_{-0.35}$ | $-6.10^{+0.48}_{-0.32}$    | $-5.97^{+0.42}_{-0.34}$    | $-9.94^{+1.67}_{-1.14}$  |
| $\text{Log}(\text{VMR}_{\text{CO}_2})$        | -3.40 | $-5.23^{+1.22}_{-1.05}$ | $-3.40^{+0.41}_{-0.47}$ | $-5.06^{+1.42}_{-0.94}$    | $-4.86^{+1.11}_{-0.96}$    | $-10.53^{+1.01}_{-0.80}$ |
| $\text{Log}(\text{VMR}_{\text{O}_2})$         | -0.67 | $-0.67^{+0.10}_{-0.08}$ | $-0.01^{+0.00}_{-0.01}$ | $-0.001^{+0.001}_{-0.001}$ | $-0.001^{+0.001}_{-0.001}$ | $-0.72^{+0.09}_{-0.08}$  |
| $\text{Log}(\text{VMR}_{\text{O}_3})$         | -6.15 | $-6.10^{+0.04}_{-0.04}$ | $-6.02^{+0.02}_{-0.02}$ | $-6.03^{+0.02}_{-0.02}$    | $-6.03^{+0.03}_{-0.02}$    | $-6.11^{+0.03}_{-0.03}$  |
| $\text{Log}(\text{VMR}_{\text{N}_2})$         | -0.11 | $-0.11^{+0.02}_{-0.03}$ | $-2.01^{+0.63}_{-1.17}$ | $-4.13^{+1.85}_{-1.62}$    | $-4.25^{+1.94}_{-1.44}$    | $-0.09^{+0.02}_{-0.03}$  |
| $M_p [M_\oplus]$                              | 1.00  | ...                     | $0.57^{+0.06}_{-0.07}$  | $0.49^{+0.04}_{-0.03}$     | $0.45^{+0.07}_{-0.05}$     | $0.99^{+0.04}_{-0.04}$   |
| $R_p [R_\oplus]$                              | 1.00  | $1.02^{+0.02}_{-0.01}$  | $1.10^{+0.02}_{-0.03}$  | $1.10^{+0.02}_{-0.02}$     | $1.11^{+0.02}_{-0.02}$     | $1.02^{+0.02}_{-0.01}$   |
| $\mu [\text{g mol}^{-1}]$ (derived)           | 28.83 | $28.85^{+0.23}_{-0.15}$ | $31.92^{+0.04}_{-0.13}$ | $31.95^{+0.01}_{-0.02}$    | $31.95^{+0.01}_{-0.02}$    | $28.75^{+0.18}_{-0.13}$  |

**Note.** The error bars of the retrieval median results correspond to the 68% confidence interval (i.e.,  $1\sigma$ ).

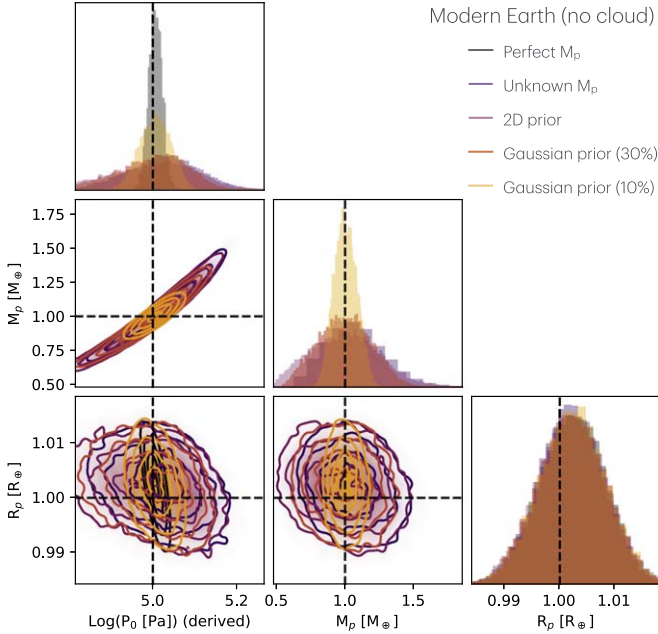
distribution of surface pressure and radius are now biased, and the planetary mass is centered at slightly smaller values. The surface pressure and the radius are inversely correlated, i.e., the larger the planet, the lower the surface pressure.

A very similar behavior is observed when running the retrieval using other types of prior functions for the planetary mass, including a Gaussian prior with a 30% standard deviation. Although conceptually, the 2D prior and the Gaussian prior are more stringent in terms of prior assumptions,

**Table 4**  
Atmospheric Parameters Used to Simulate the Archean Earth-like Scenario and the Retrieval Results for the Five Scenarios Considered

| Parameter                                     | Input | Perfect $M_p$           | Unknown $M_p$           | 2D prior                | Gaussian Prior (30%)    | Gaussian Prior (10%)    |
|---|-------|-------------------------|-------------------------|-------------------------|-------------------------|-------------------------|
| $\text{Log}(P_0)$ [Pa] (derived)              | 5.00  | $4.89_{-0.04}^{+0.07}$  | $5.12_{-0.15}^{+0.16}$  | $5.06_{-0.12}^{+0.09}$  | $4.95_{-0.09}^{+0.08}$  | $4.95_{-0.05}^{+0.05}$  |
| $\text{Log}(P_{\text{top,H}_2\text{O}})$ [Pa] | 4.78  | $4.40_{-0.14}^{+0.18}$  | $4.51_{-0.16}^{+0.17}$  | $4.47_{-0.14}^{+0.13}$  | $4.40_{-0.13}^{+0.12}$  | $4.57_{-0.14}^{+0.13}$  |
| $\text{Log}(D_{\text{cld,H}_2\text{O}})$ [Pa] | 4.00  | $4.19_{-0.22}^{+0.17}$  | $4.40_{-0.24}^{+0.22}$  | $4.32_{-0.23}^{+0.20}$  | $4.23_{-0.23}^{+0.19}$  | $4.31_{-0.17}^{+0.13}$  |
| $\text{Log}(\text{CR}_{\text{H}_2\text{O}})$  | -3.50 | $-5.01_{-1.27}^{+1.42}$ | $-4.95_{-1.40}^{+1.52}$ | $-4.93_{-1.35}^{+1.45}$ | $-4.92_{-1.36}^{+1.39}$ | $-5.40_{-0.95}^{+1.09}$ |
| $\text{Log}(\text{VMR}_{\text{H}_2\text{O}})$ | -1.00 | $-0.77_{-0.21}^{+0.19}$ | $-0.77_{-0.18}^{+0.15}$ | $-0.74_{-0.16}^{+0.15}$ | $-0.72_{-0.17}^{+0.16}$ | $-0.89_{-0.15}^{+0.17}$ |
| $\text{Log}(\text{VMR}_{\text{CH}_4})$        | -2.00 | $-1.66_{-0.23}^{+0.09}$ | $-1.56_{-0.08}^{+0.07}$ | $-1.58_{-0.07}^{+0.07}$ | $-1.61_{-0.08}^{+0.07}$ | $-1.90_{-0.09}^{+0.11}$ |
| $\text{Log}(\text{VMR}_{\text{CO}_2})$        | -1.00 | $-0.16_{-0.50}^{+0.07}$ | $-0.11_{-0.06}^{+0.03}$ | $-0.11_{-0.05}^{+0.03}$ | $-0.12_{-0.08}^{+0.04}$ | $-0.66_{-0.17}^{+0.19}$ |
| $\text{Log}(\text{VMR}_{\text{O}_2})$         | -7.00 | $-4.23_{-1.80}^{+1.50}$ | $-4.31_{-1.85}^{+1.64}$ | $-4.39_{-1.71}^{+1.64}$ | $-4.42_{-1.68}^{+1.67}$ | $-6.68_{-3.19}^{+2.96}$ |
| $\text{Log}(\text{VMR}_{\text{N}_2})$         | -0.10 | $-2.11_{-3.36}^{+1.92}$ | $-3.86_{-2.24}^{+2.34}$ | $-3.91_{-2.14}^{+2.34}$ | $-3.78_{-2.07}^{+2.56}$ | $-0.21_{-0.10}^{+0.07}$ |
| $M_p [M_\oplus]$                              | 1.00  | ...                     | $1.77_{-0.51}^{+0.80}$  | $1.56_{-0.40}^{+0.34}$  | $1.20_{-0.21}^{+0.24}$  | $1.01_{-0.07}^{+0.08}$  |
| $R_p [R_\oplus]$                              | 1.00  | $1.01_{-0.01}^{+0.01}$  | $1.01_{-0.01}^{+0.01}$  | $1.01_{-0.01}^{+0.01}$  | $1.01_{-0.01}^{+0.01}$  | $1.01_{-0.01}^{+0.01}$  |
| $\mu [\text{g mol}^{-1}]$ (derived)           | 28.49 | $36.16_{-6.09}^{+2.92}$ | $38.46_{-2.17}^{+1.55}$ | $38.21_{-2.85}^{+1.71}$ | $37.85_{-2.14}^{+1.59}$ | $29.90_{-1.02}^{+1.93}$ |

**Note.** The error bars of the retrieval median results correspond to the 68% confidence interval (i.e.,  $1\sigma$ ).

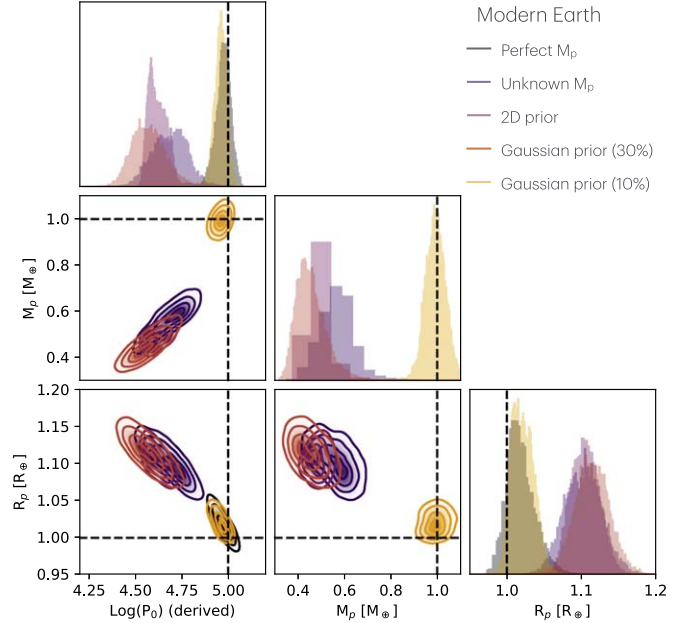


**Figure 4.** Posterior distribution functions for planetary mass, radius, and surface pressure for the cloud-free modern Earthlike scenario. The surface pressure is a proxy for the atmospheric gases collectively as the sum of their partial pressure is equal to the surface pressure.

the retrieved planetary mass remains consistent with that of the unknown mass prior scenario. Finally, when a Gaussian prior with a 10% standard deviation is used for the planetary mass, the prior constraint becomes sufficient to correctly identify the atmospheric components and other free parameters (Figure 7). This result underlines how a tight prior knowledge of the mass is needed to correctly identify the background gas and the surface pressure on an Earthlike exoplanet.

### 3.3. Archean Earth-like

Given the results of the modern Earthlike scenario, we decided to test the same set of mass uncertainties on a different kind of atmosphere. The Archean Earth-like planet has considerably less oxygen and more  $\text{CO}_2$  than the modern Earthlike planet. This way we can test if the misinterpretation



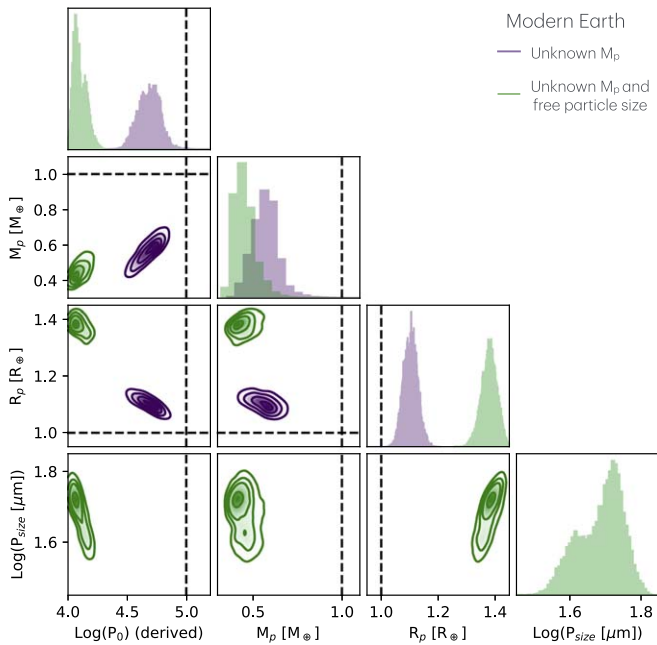
**Figure 5.** Posterior distribution functions for planetary mass, radius, and surface pressure for the modern Earthlike scenario. The surface pressure is a proxy for the atmospheric gases collectively as the sum of their partial pressure is equal to the surface pressure.

of the background gas is linked to  $\text{O}_2/\text{N}_2$  correlations or if they are an effect of the mass uncertainty more generally.

As in the case of the modern Earthlike scenario, we started by fixing the planetary mass. In this case (Figure 8), we retrieved all the parameters correctly, i.e., the truth values are encompassed within the posterior distributions. Using this as the baseline scenario, we then included the mass as a free parameter and explored the different prior functions for the planetary mass described in Section 2.2.

Similarly to the modern Earthlike scenario, we find that the background gas would be incorrectly identified if the planetary mass is not known to be better than  $\sim 10\sigma$  (Figure 8). Here, the retrieval settled on  $\text{CO}_2$  rather than  $\text{N}_2$  as the background gas if the mass is not assumed to be well known. This shows that the misinterpretation of the background gas does not seem to be related to  $\text{O}_2$  particularly but rather to how the retrieval





**Figure 6.** Posterior distribution functions for planetary mass, radius, surface pressure, and particle size for the modern Earthlike scenario. The surface pressure is a proxy for the atmospheric gases collectively as the sum of their partial pressure is equal to the surface pressure.

interprets the gases that have strong spectral features versus the gases that do not. Misidentification of the dominant gas causes biases in the estimates of other gases. For example,  $\text{CH}_4$  was retrieved slightly higher than the input value.  $\text{H}_2\text{O}$  was correctly constrained, and  $\text{O}_2$  was unconstrained as expected, as there are no measurable spectral features with an input value of  $10^{-7}$ . The cloud deck was overall correctly identified. The position is slightly higher and slightly deeper than the input cloud, but still within  $3\sigma$  from the input values.

Meanwhile, even though the mass was allowed to span up to  $20 M_\oplus$ , the retrieval converged to a small range around the true value, confirming that the spectrum indeed contains information about the planetary mass. With a flat prior on the mass, we find a broad posterior distribution centered at larger values (i.e.,  $1.77^{+0.80}_{-0.51} M_\oplus$ ), with the planetary radius retrieved correctly with a tight constraint around  $1 R_\oplus$ . Using the 2D prior on the planetary mass and radius tightens the mass constraints to  $1.56^{+0.34}_{-0.40} M_\oplus$ , as the mass now depends on the value of the radius. This result suggests that, in some cases, the spectrum alone can give planetary mass constraints to  $\sim 3\sigma$ .

Giving a closer look at the correlations between key parameters (Figure 9), we observe that the planetary mass and the surface pressure also in this case appear to be correlated. The correlation appears to be similar to the one observed in both previous atmospheric scenarios (see Figures 4 and 5), with a tighter mass constraint leading to a tighter constraint on the surface pressure. Unlike the modern Earthlike with clouds scenario, we do not observe correlations between the planetary radius and the other two parameters.

Moreover, as in the case of the modern Earth analog, we consider a variation of this first case for the Archean Earth analog by including the cloud particle size as a free parameter (Figure 10). Differently from the modern Earthlike scenario, we do not observe biases; however, we notice that the posterior distribution of surface pressure, mass, and radius have longer tails toward larger values, and the planetary mass can now

stretch to  $>6 M_\oplus$ . While the retrieved value for the particle size largely agrees with the self-consistent formulation used to synthesize the spectrum in the first place, treating the cloud particle size as a free parameter notably degrades the mass constraints obtained from the spectrum.

## 4. Discussion

### 4.1. Comparison with Previous Studies

A. Salvador et al. (2024) explored the impact of prior knowledge of planetary mass and orbital parameters on the atmospheric characterization of directly imaged Earthlike exoplanets in reflected light. The authors simulated observations of a modern Earth analog obtained by future missions like the Habitable Worlds Observatory. They performed atmospheric retrievals under varying levels of prior information, including scenarios with no prior constraints on planetary orbit and mass, known orbit, known orbit and mass, and only mass constrained.

The study finds that prior knowledge of orbit-related parameters, such as orbital distance and phase angle, significantly improves the determination of the planetary radius from reflected light observations, thereby helping to identify the planet's type and density. This improvement arises due to a strong degeneracy between the orbit and radius in the planet-to-star flux ratio. However, additional prior knowledge of the planet's mass does not notably enhance radius determination or atmospheric characterization in that study.

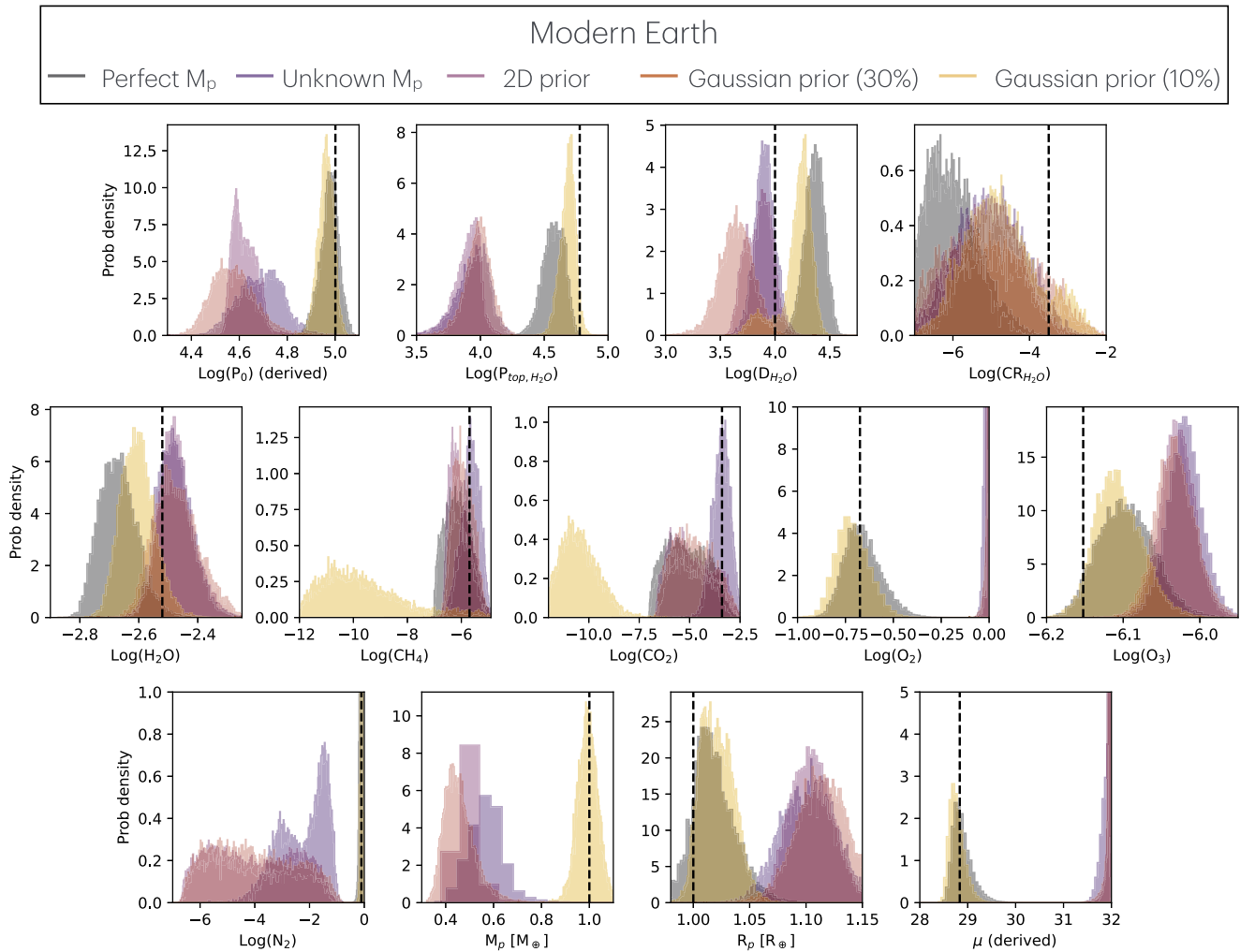
In this study, we assume that the planetary orbit has been constrained within reasonable error bars so that the position of the planet in its orbit would be known. Once the orbit is known, the characterization observation can be scheduled, and the reflected spectrum of the planet can be observed. In this work, we focused more on the interaction between the planetary mass and the atmospheric composition. The results shown in this paper agree with A. Salvador et al. (2024) in the sense that the spectrum can generally constrain the planetary radius when the orbital configuration is known. We do see that the spectrum contains some information about the mass, and when imposing the 2D prior introduced in this paper, the mass may even be constrained from the spectrum alone in some cases (Figure 9). However, as a crucial revelation, our results suggest that the ability to retrieve the background gas hinges on highly precise prior mass constraints.

### 4.2. Identification of the Background Gas

Misidentifying the background gas can be a substantial issue as it can render a habitable planet (moderate concentration of  $\text{O}_2$ ) into a postrunaway, inhospitable world (massive  $\text{O}_2$ -dominated atmosphere). Indeed, the identification of  $\text{O}_2$  as a biosignature relies on the knowledge that the background atmosphere is not  $\text{O}_2$  dominated (R. Wordsworth & R. Pierrehumbert 2014; C. E. Harman et al. 2015; V. S. Meadows 2017; L. Sproß et al. 2021).

In this work, we showed that the lack of precise planetary mass prior knowledge will likely prevent the background gas from being correctly identified, even with a spectrum that covers from the UV to the NIR. In the case of the modern Earth analog with clouds,  $\text{N}_2$  is misidentified as  $\text{O}_2$ , and in the case of the Archean Earth-like planet, the  $\text{N}_2$  is misidentified as  $\text{CO}_2$ . In both cases, the common factor is an active absorbing gas versus a gas that does not show absorption features in the





**Figure 7.** Posterior distribution functions of the Bayesian analysis on the modern Earthlike reflected spectrum of all the scenarios defined in Section 2.1.5.

considered wavelength range. Not having a mass constraint equates to not having a surface gravity constraint, and this affects the calculation of the atmospheric scale height. The retrieval algorithm seeks to balance the difference in the scale height with different mean molecular masses. In the case of modern Earth, the two most abundant gases have close mean molecular mass (28 for  $N_2$  and 32 for  $O_2$ ), and the mass constraints must be stringent enough to distinguish between the two. For the Archean Earth analog, instead, the difference between  $N_2$  and  $CO_2$  in terms of mean molecular mass is greater (28 for the former and 44 for the latter), and we see that different constraints on the planetary mass are indeed reflected in the posterior distribution of  $N_2$  and  $CO_2$ . A strong fit of the Rayleigh scattering will help in the identification of the background gas (see Section 3.1). However, the presence of clouds tends to mute the Rayleigh feature, making it more challenging to uniquely associate it with the background gas.

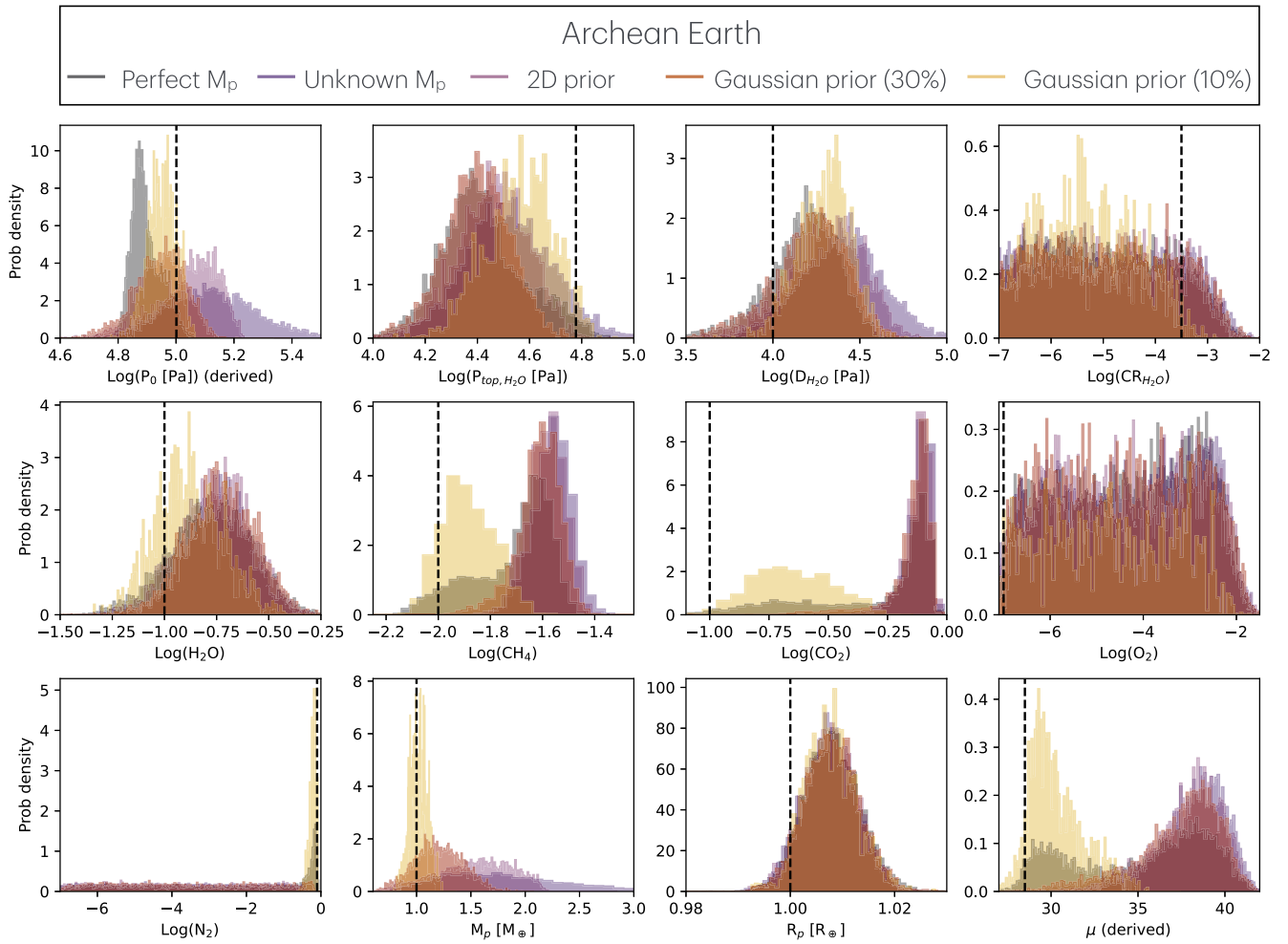
#### 4.3. Toward 10% Mass Uncertainty

Radial Velocity (RV) observations are the most successful tool to date for determining the masses of small exoplanets. Measurements of a star's radial velocity (RV) made using stable, high-resolution, optical, or NIR spectrographs can be used to determine the orbital parameters of the exoplanets it hosts (C. Lovis & D. Fischer 2010). Time series measurements

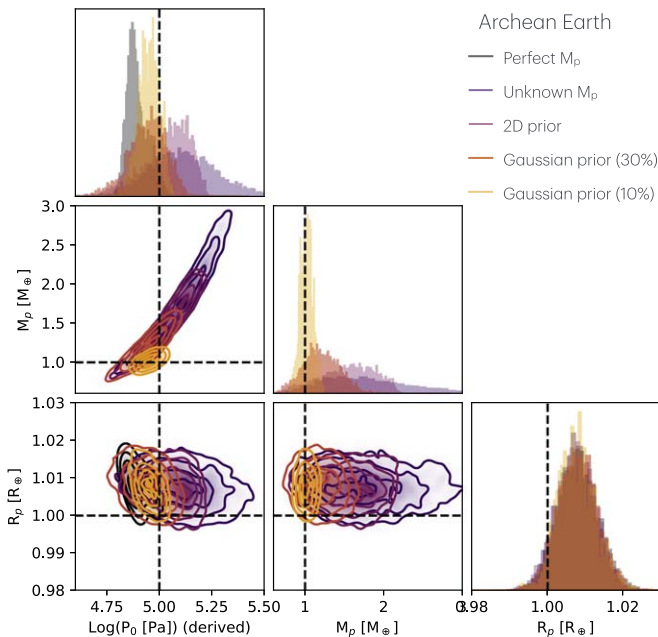
of Doppler shifts in the star's spectral lines that are caused by the gravitational influence of an orbiting planet allow for the derivation of the planet's minimum mass ( $M_p \sin(i)$ ), where  $i$  is the inclination of the planet's orbital plane relative to the line of sight.

Most RV-discovered planets to date, where no precise period and orbital phase priors are provided by accompanying transit detections, have RV semi-amplitudes  $K > 1 \text{ m s}^{-1}$ . This limit is set primarily by the presence of stellar phenomena such as star spots, plage, and granulation, which can deform stellar absorption features and obscure Keplerian Doppler signals (see, e.g., N. Meunier et al. 2010; A. Collier Cameron et al. 2019). The RV semi-amplitudes of an Earth-mass planet orbiting at the Earth Equivalent Irradiation Distance around likely HWO target stars (E. Mamajek & K. Stapelfeldt 2024) ranges from 5 to  $50 \text{ cm s}^{-1}$ , notably smaller than the current state of the art. Achieving the 10% mass uncertainty recommended in this study will therefore require that the uncertainties of the relative RV measurements be  $\leq 10 \text{ cm s}^{-1}$  over timescales of years to decades so that systematic errors do not dominate the planet signals (J. K. Luhn et al. 2023).

While  $10\sigma$  mass measurements ( $\sigma_{m_{\text{pl}}} / m_{\text{pl}} \geq 10$ ) of Earth analogs have not yet been demonstrated, the development of a new generation of Extreme Precision RV (EPRV) instruments including ESPRESSO (F. Pepe et al. 2021), NEID



**Figure 8.** Posterior distribution functions of the Bayesian analysis on the Archean Earth-like reflected spectrum of all the scenarios defined in Section 2.1.5.

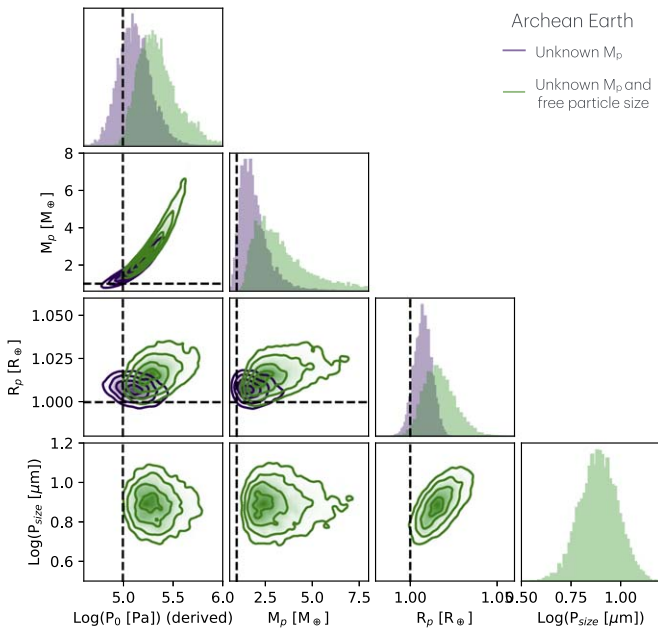


**Figure 9.** Posterior distribution functions for planetary mass, radius, and surface pressure for the Archean Earth-like scenario. Note that the surface pressure is a proxy for the atmospheric gases collectively as the sum of their partial pressure is equal to the surface pressure.

(C. Schwab et al. 2016), EXPRES (R. R. Petersburg et al. 2020) and KPF (S. R. Gibson et al. 2024) has improved the precision of single RV measurements to  $\sim 30 \text{ cm s}^{-1}$ . And dedicated treatment of instrument systematics and stellar activity in long baseline RV time series from the previous generation of stabilized RV instruments has demonstrated Doppler Sensitivity at the  $50\text{--}60 \text{ cm s}^{-1}$  level over timescales of 1–2 yr (see, e.g., M. Cretignier et al. 2023; A. A. John et al. 2023).

Further improvements to both instrument performance and stellar variability modeling/mitigation will be required in the coming years to advance extreme precision RV (EPRV) capabilities, but these recent results show promising forward momentum. We note, however, that the radial velocity method alone measures only the projected mass of the planet, leaving its true mass uncertain. We also note that stars above the Kraft break ( $T_{\text{eff}} \geq 6250 \text{ K}$ ) will not be amenable to EPRV measurements because their fast rotation periods produce significant rotational broadening, thereby decreasing the amount of Doppler information content contained within their spectra (T. G. Beatty & B. S. Gaudi 2015).

Astrometry is another powerful technique for determining the masses of exoplanets. By precisely tracking the star's motion on the plane of the sky over time, astrometry could provide a direct measurement of the planet's mass without the  $\sin i$  ambiguity inherent in radial velocity methods, as it is



**Figure 10.** Posterior distribution functions for planetary mass, radius, surface pressure, and particle size for the Archean Earth-like scenario. The surface pressure is a proxy for the atmospheric gases collectively as the sum of their partial pressure is equal to the surface pressure.

sensitive to the inclination of the orbit (S. C. Unwin et al. 2008). In the context of the HWO, astrometry could play a crucial role in directly measuring the masses of small terrestrial planets (F. Malbet et al. 2012; A. Quirrenbach et al. 2014). The combination of astrometric measurements from HWO with its direct imaging capabilities can yield both the mass and orbital parameters of Earth-sized planets in the habitable zones of nearby stars, enhancing our understanding of their potential habitability (National Academies of Sciences & Medicine 2021).

## 5. Conclusion

In this study, we explored the impact of planetary mass uncertainties on the atmospheric retrieval of terrestrial exoplanets observed in the reflected light. Utilizing an enhanced version of EXOREL<sup>3</sup>, we incorporated several upgrades, including cloud fraction modeling, composition-dependent Rayleigh scattering, an adaptive vertical grid, partial pressure sampling, and the inclusion of planetary mass as a free parameter with various prior probability functions. We also introduced a method to more realistically calculate the error bars of the simulated spectrum. This new routine takes into consideration the star photon noise, exozodi approximation, and spectral resolution of the simulated data; and analytically calculates the signal-to-noise per spectral element.

Our retrieval analyses were conducted on three atmospheric scenarios: a cloud-free modern Earthlike atmosphere, a modern Earthlike atmosphere with a cloud deck, and an Archean Earth-like atmosphere. We considered different prior knowledge of the planetary mass, ranging from perfectly known mass to scenarios with varying degrees of uncertainty.

The results indicate that precise knowledge of the planetary mass is needed for accurate atmospheric characterization of small rocky planets. When the planetary mass is known within 10% uncertainty, the retrievals successfully identify the background gas and constrain atmospheric parameters, even in the presence of clouds. However, with less constrained or

unknown mass, we observed significant biases in the retrievals, particularly in the misidentification of the dominant atmospheric gas. For instance, nitrogen was incorrectly replaced by oxygen or carbon dioxide, which could lead to incorrect assessments of planetary habitability and biosignatures.

These biases arise because uncertainties in planetary mass affect the determination of surface gravity and atmospheric scale height, leading the retrieval algorithm to compensate by adjusting the atmospheric composition. While some information about the planetary mass can be inferred from the reflected spectrum alone, it is insufficient to accurately constrain the mass and the bulk atmospheric composition without additional prior information.

In this work, we did not explore the impact of mass uncertainty on characterizing larger planets (e.g., super-Earths versus sub-Neptunes), nor higher spectral resolution or signal-to-noise ratios. Nonetheless, our simulations highlight the importance of achieving precise mass measurements of small terrestrial exoplanets—ideally within 10% uncertainty—through methods such as Extreme Precision Radial Velocity or astrometry, especially in the context of missions like the Habitable Worlds Observatory. Accurate mass constraints are important to reliably characterize exoplanet atmospheres and to correctly interpret potential biosignatures. Future observational strategies should prioritize obtaining accurate mass measurements to improve the characterization of exoplanetary atmospheres and to better assess their potential habitability.

## Acknowledgments

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*Software:* NUMPY (T. Oliphant 2015), SCIPY (P. Virtanen et al. 2020), ASTROPY (Astropy Collaboration et al. 2013, 2018, 2022), MATPLOTLIB (J. D. Hunter 2007), MULTINEST (F. Feroz et al. 2009; J. Buchner et al. 2014), MPI4PY (L. Dalcin & Y.-L. L. Fang 2021).

## Appendix Noise Model

There are multiple sources of noise in a coronagraphic image or spectrum including detector noise, host star residual speckles after point-spread function (PSF) subtraction, and shot noise from the planet, local zodi, exozodi, and the host star raw speckles. The relative strengths of these various noise sources will depend on the instrument architecture and the observational target. For example, coronagraphs require active wave front control and therefore achieve higher performance on brighter host stars; and planet radius, orbital distance, albedo, and host star type all contribute to the observed flux ratio.

The noise model used for this study represents a simplistic limiting case with very good starlight suppression and low detector noise, in which photon noise from the astrophysical scene dominates. We follow the analytic prescription outlined in T. D. Robinson et al. (2016). We can assume exozodi dominate over local zodi, and neglect local zodi. Dark current

is also ignored, assuming that a future exoplanet imaging mission will have good enough detectors that the dark current will be lower than photon noise at all wavelengths, as is already the case for the Roman CGI in broadband imaging (P. Morrissey et al. 2023). The speckle residuals are likewise neglected. This leaves the shot noise from the planet and the exozodi as the only remaining noise sources.

Future mission concept studies would use more realistic noise models that are representative of the chosen architecture. However, as we normalize the noise to the desired SNR, the main difference between this model and the “full” model is the color of the noise, rather than the magnitude. Running the retrieval with different colors of noise was outside the scope of this research.

The planet's photoelectron count rate at the detector within an aperture is:

$$c_{p,\lambda} = F_{p,\lambda} \frac{\lambda}{hc} \pi \left( \frac{D}{2} \right)^2 \Delta \lambda \mathcal{T}_\lambda f_{ap} \propto F_{p,\lambda} \lambda \Delta \lambda, \quad (\text{A1})$$

where  $\frac{\lambda}{hc}$  is the photon energy,  $\Delta \lambda$  is the bandwidth of the filter or spectral resolution element,  $D$  is the telescope diameter, and  $\mathcal{T}_\lambda$  is the effective system throughput (detector quantum efficiency and optical throughput), and  $f_{ap}$  is the fraction of planet light within the aperture (sometimes also called the “core throughput”; in the coronagraphic case this also accounts for losses due to the coronagraph masks and wave front control). We assume  $\mathcal{T}_\lambda$  and  $f_{ap}$  are wavelength independent.

For extended surface brightness sources, such as exozodi, the count rate is

$$c_{ez,\lambda} = F_{ez,\lambda} \frac{\lambda}{hc} \pi \left( \frac{D}{2} \right)^2 \Delta \lambda \mathcal{T}_\lambda \Omega \propto F_{s,\lambda} \lambda^3 \Delta \lambda, \quad (\text{A2})$$

where  $\Omega$  is the aperture size. In this case we assume an aperture proportional to the PSF width, therefore  $\Omega \propto \lambda^2$ . We assume exozodi are gray ( $F_{ez,\lambda} \propto F_{s,\lambda}$ ).

To calculate the total noise, we combine the noise sources with appropriate weights. The total count rate for photon noise is given by

$$c_{r,\lambda} = c_{p,\lambda} + \alpha c_{ez,\lambda}. \quad (\text{A3})$$

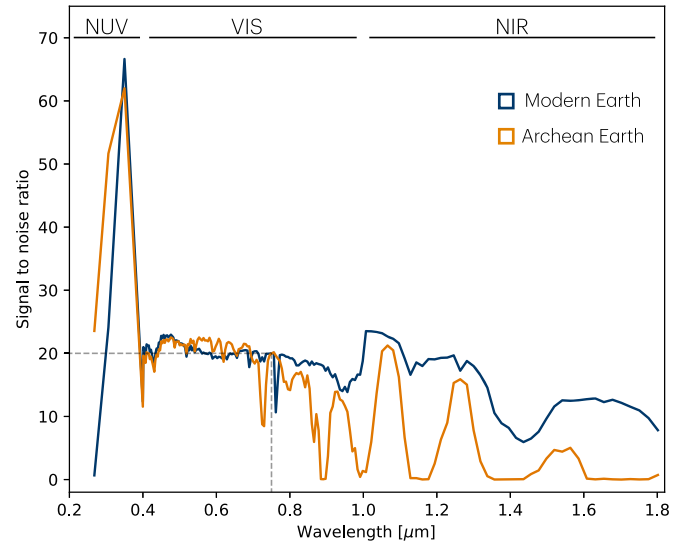
The SNR for a given exposure time can then be calculated as

$$\text{SNR} = \frac{c_{p,\lambda} t_{\text{exp}}}{\sqrt{(c_{p,\lambda} + \alpha c_{ez,\lambda}) t_{\text{exp}}}}. \quad (\text{A4})$$

Substituting the definitions for each term allows us to investigate the proportionality with wavelength and spectral bin width:

$$\text{SNR} = \beta F_{p,\lambda} \sqrt{\frac{\lambda \Delta \lambda}{F_{p,\lambda} + \alpha F_{s,\lambda} \lambda^2}} \quad (\text{A5})$$

$\alpha$  and  $\beta$  are weights chosen to scale the noise terms and the overall SNR to the desired values. According to R. Hu et al. (2021), the flux of the exozodi should be roughly half that of the planet at  $0.7 \mu\text{m}$ , assuming an Earthlike planet in the HZ of an FGK star at 6 pc, and assuming that the system has three zodi (as is the assumption adopted by various mission concept studies and yield analyses (S. Seager et al. 2019; C. C. Stark et al. 2019; B. S. Gaudi et al. 2020)). Thus  $\alpha$  is chosen such that  $F_{p,\lambda} = 2\alpha F_{s,\lambda} \lambda^2$  at  $0.75 \mu\text{m}$ .  $\beta$  is chosen to scale the noise



**Figure 11.** SNR vs.  $\lambda$  for the modern and Archean Earth scenarios. The SNR is set to be 20 at  $0.75 \mu\text{m}$ . The jump at  $1 \mu\text{m}$  is due to the fact that in the NIR, the spectral resolution decreases from  $R = 140$  to  $R = 70$ . Similarly, the jump at  $0.4 \mu\text{m}$  is due to the drop in spectral resolution in the NUV, i.e.,  $R = 7$ .

such that an SNR of 20 is achieved at  $0.75 \mu\text{m}$ . This wavelength was chosen as it is on the continuum for all three scenarios analyzed in this paper, and it is next to the  $\text{O}_2$  absorption feature at  $0.76 \mu\text{m}$ .

The resulting SNR versus wavelength for the modern and Archean Earth scenarios are shown in Figure 11.

## ORCID iDs

Mario Damiano <https://orcid.org/0000-0002-1830-8260>  
 Zachary Burr <https://orcid.org/0009-0000-4845-3613>  
 Renyu Hu <https://orcid.org/0000-0003-2215-8485>  
 Jennifer Burt <https://orcid.org/0000-0002-0040-6815>  
 Tiffany Kataria <https://orcid.org/0000-0003-3759-9080>

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